

## **PICAXE Module Questions**

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Read through the PICAXE Getting Started manual (picaxe\_manual1.pdf) and answer the following question. The answers must be cut and paste from the .pdf file to your word processing document.

## Part 1

- 1. What is a microcontroller?
- 2. List the advantages of using microcontrollers in a product design.
- 3. List some of the applications microcontrollers are used in.
- 4. What programming language does the PICAXE use and why?
- 5. Other than BASIC, how can the PICAXE be programmed?
- 6. What is a mechatronic system?
- 7. What is an input transducer?
- 8. List some input transducers.
- 9. What is an output transducer?
- 10. List some output transducers.
- 11. What does the PICAXE bootstrap code do?
- 12. Identify the five things that are required to use the PICAXE system.
- 13. What operating system is required to run the software?
- 14. How does the download cable connect to the computer?
- 15. What are the four sizes of PICAXE?
- 16. For the 18 pin PICAXE, what are the 3 variants?
- 17. What variants can do higher resolution ADC?
- 18. What variants can do the PWM motor control?
- 19. On the computer, what are the 9 pin serial ports identified as?
- 20. List the battery configurations that are allowed and what isn't allowed.

## Part 2

- 21. Draw and label the 7805 voltage regulator circuit. Also draw and label the large component.
- 22. Draw out the PICAXE 18X minimum operating circuit and label the pins on the chip.
- 23. What must be done to the Reset pin?
- 24. What does it mean to have a microcontroller 'over-clocked'?
- 25. Draw the minimum download circuit showing how it hooks up to the PICAXE using the straight header pins and how it connects to the computer.
- 26. Using the above diagram, create a table showing the connections from the PICAXE to the computer.
- 27. What is a hard reset and what are the steps?
- 28. What are the main categories for a download checklist?
- 29. Identify the three types of memory and list some of their characteristics.
- 30. What are general purpose variables?

- 31. Who is the flowcharting method of programming designed for?
- 32. What is the drawback of this method of programming?
- 33. What is Basic Simulation?
- 34. What is the maximum current the PICAXE microcontrollers can source or sink on the output pins?
- 35. What component must be used to source higher current output devices?
- 36. Draw how a motor can be connected to an output pin.
- 37. Draw how a digital input must be connected.
- 38. For an analogue input, what caution must be observed?
- 39. Identify and describe the three main components of the PICAXE system. What does the apostrophe indicate?

## Part 3

- 40. What does the colon indicate?
- 41. What is the difference between wait and pause?
- 42. What is white space and how does it relate to good programming techniques?
- 43. What programming technique can be used when part of the program has to be repeated?
- 44. What command is recommended to play musical tunes?
- 45. Draw the schematic symbol for Piezo Sounder.
- 46. Name three digital sensors that could be used as an input.
- 47. When using analogue sensors, what is the number range that can be used to represent a varying voltage signal?
- 48. List three analogue sensors.
- 49. What does the debug command do?
- 50. What does the Sertxd command do?
- 51. Define bit, byte, LSB, and MSB.
- 52. What does the **let pins** command do?
- 53. What are Sub-procedures and why are they used?
- 54. List all of the PICAXE 18X commands.